BACHELOR THESIS



MODEL FITTING FOR ALTERNATIVE STATISTICAL MODELS FOR BINARY SURVEY DATA

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Abstract

Strong empirical evidence suggests that respondents are more likely to respond truthfully to a sensitive question if they feel that the anonymity and confidentiality of their response is granted. The Randomized Response Technique provides an approach to increase the response accuracy on sensitive questions while allowing a valid estimation of the prevalence of illegal or socially undesirable behavior and attitudes in the population. It was assumed that existing goodness-of-fit tests are suited for Randomized Response designs with binary data if the link function is adjusted. The assumption was evaluated in a simulation study for categorical and continuous data. Across a total amount of 210000 randomly generated samples, no significant difference in type-1 errors was found between randomized data and non-randomized data. The statistical power declined as the degree of randomization of the data was increased. No difference between categorical and continuous data was found. The obtained results strongly indicate that existing goodness-of-fit tests can be utilized for Randomized Response designs with binary data.

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1. Introduction

1.1 Surveys

During the past decades surveys have served a major role in collecting empirical data for the purpose of social observational studies. In general, a survey consists out of a set of questions or statements that, when answered, judged or commented by a representative sample of respondents, give insight into the prevalence of one or more predefined constructs within the population the study is aimed at. For example, a study aiming to explore the construct of intrinsic motivation among students of Dutch universities could utilize a survey that contains a set of questions that cover all aspects of the construct intrinsic motivation. As it is often impracticable to collect data from the whole population, in this case the data of all students of Dutch universities, a representative sample is being studied. In other words, a sample of the population takes the survey which yields data that aims to be representative for the whole population.

1.2 Error and bias

Even though there exists a great variety of methods when it comes to selecting a sample (Hibberts et al., 2012), it is virtually impossible to draw a sample that perfectly represents the population that it is drawn from. The difference between the data obtained through applying a sampling method and the true values, as present in the population, is called the sampling error. If the difference randomly varies with each sample taken, this error is also referred to as random error. Random error must be distinguished from systematic error, or bias, which describes a systematic difference in one direction.

According to the Total Survey Error approach, error within survey studies can be discriminated into three categories (Weisberg, 2005). The first category leads to what is also called the sampling error, while the second and third category is often unified as the nonsampling error (Krumpal, 2011). First of all, error can occur at the selection of respondents, for example in the form of nonresponse bias or sampling bias. Nonresponse bias means that members of a sample do not become respondents due to a common characteristic, e.g. if the survey is offered solely in Dutch, international students that do not speak Dutch systematically will not participate. If the respondents are not selected randomly but for example by asking for volunteers through a notice at the bulletin board then this results in an availability sample which can lead to sample bias, e.g. students with

high intrinsic motivation are more likely to voluntarily take part in a study that does not lead to an extrinsic reward such as extra study points or money.

Second, error can be introduced when processing and analyzing the data as well as when reporting the results. Potential causes of postsurvey error are mistakes that might occur when entering the data from a pen-and-paper survey into a computer and applying the wrong statistical method which leads to a false estimation of the prevalence of the studied construct in the population.

And finally, a variety of factors influence the accuracy of the responses. In surveys, the accuracy of a response can be defined as the extent to which the respondent answers in accordance with the intentions of the researcher (Weisberg, 2005). Weisberg (2005) furthermore separates response accuracy as measurement error and nonresponse error. Measurement error can be caused either by the interviewer or the respondent. Interviewerrelated measurement error occurs if the observed responses differ because of the interviewer. Respondent-related measurement error reflects the discrepancy between the expected and the observed value. This can range from simple factual checks, e.g. "Did you ever drink and drive?" in which the researcher expects an answer that matches reality, to questions about attitude, e.g. "Do you think driving under the influence of alcohol should be punished more severely?" on which the respondent should provide an answer that is in accordance with the theoretical model. In other words, if the theoretical model expects that a respondent who scores high or low on a certain construct provides certain answers, then any discrepancy between the expected and the observed value increases the measurement error, lowers the response accuracy, and hence contributes to the total error of the survey. In some cases a respondent is unable or not willing to answer a question, which causes nonresponse error at the item level. Nonresponse error at the item level often leads to biased results as the likelihood to respond to a particular question can be governed by certain characteristics of the respondent, such as his attitudes and his current or past behavior.

1.3 Sensitive questions and response accuracy

Questions about topics that are perceived as private or taboo by the respondent, such as sexual behavior, as well as questions about attitudes and activities that are in contradiction with social norms lead to a lower response accuracy (Tourangeau & Yan, 2007).

Tourangeau, Rips, and Rasinski (2000) identified three aspects of these so-called sensitive questions which affect the response accuracy.

The first aspect of sensitivity is the intrusiveness of a question. A question is intrusive to a respondent if he feels like it invades his privacy by touching a topic that he considers too private or taboo. Examples of topics that are commonly regarded as intrusive refer to the income (Moore et al., 2000) and the sexual behavior of the respondent (Fenton et al., 2001). Another aspect that affects the sensitivity of a question is the perceived risk of disclosure and possible negative consequences of providing a truthful answer. A student might for example hesitate to truthfully respond to a question about committing fraud during exams as he fears that his response might be disclosed, leading to a severe punishment by his university. Lastly, the sensitivity of a question is influenced by social desirability. Randall and Fernandes (1991) describe social desirability in terms of two dimensions: a personal dimension and an item-related dimension. The personal dimension refers to the respondent's need of approval as a stable trait. According to the item-related dimension, respondents judge possible answers of questions based on how far these answers conform with social norms. From that follows that the degree of perceived sensitivity of a question depends on the respondent's need of approval and how the respondent judges the social desirability of the answer that he is supposed to present under the condition of answering truthfully.

To sum up, the perceived sensitivity of a question depends as well on the question as on the answer. A question can touch topics that are too private for the respondent to talk about, regardless of possible answers. On the other hand, whether or not social desirability influences the perceived sensitivity of a question depends on if the respondent's truthful answer is in conformance with social norms. To illustrate this with an example, the question "How many sexual partners have you had in the past year?" is likely to be perceived as touching on a private topic and thus as sensitive while the question "Have you ever committed rape?" is perceived as sensitive only by those respondents that would answer with a "yes". Finally, the perceived risk of disclosure contributes to the perceived sensitivity of a question.

1.4 Increasing the response accuracy on sensitive questions

First described by Warner (1965), the random response technique (RRT) offers a solution to questions being perceived as sensitive and thus lowering the response accuracy. Contrary to

traditional direct questioning (DQ) methods, the RRT does not require the respondent to reveal his answer to the researcher. Instead, using a randomizing device, e.g. rolling a dice, the respondent decides whether he presents his truthful answer or a prescribed response. The researcher has no insight into the randomizing device and thus the anonymity and confidentiality of the respondent is granted. In other words, it is not possible for the researcher to identify the information that belongs to a certain respondent and it is also not possible to identify the respondent by the information he provided. This successfully addresses the sensitivity of questions, the sensitivity of answers and the fear of disclosure. While the researcher cannot draw conclusions about a single respondent, there is strong evidence that applying the RRT can lead to a valid estimation of the prevalence of illegal or socially undesirable behavior and attitudes in the population (Lensvelt-Mulders et al., 2005; Silva & Vieira, 2009; Simon et al., 2006).

2. Representing Randomized Response Models in Generalized Linear Models

2.1 Predicting responses using linear regression

Imagine a researcher theorizing that the performance on a particular task of university students depends on the students' intrinsic motivation towards their study and their intelligence. Here, we have three variables: the response variable y_i , which is the measured task performance in a controlled laboratory environment of the *i*-th student, and a set of two explanatory variables x_{i1} and x_{i2} , representing the intrinsic motivation of the *i*-th student, respectively his intelligence. By applying linear regression to the data gained through a drawing a sample, the researcher can create a function $f(x_i)$, with x_i being a vector of explanatory variables to predict the response variable y_i . More concrete, applying linear regression leads the a linear function $f(x_i)$, that consists out of the explanatory variables x_{i1} ... x_{in} , a constant β_0 and the regression coefficients $\beta_1 \dots \beta_n$ that determine the weight of the *j*-th explanatory variable x_{ij} in predicting y_i . From that follows the equation

$$\hat{y}_i = f(x_i) = \beta_0 + \beta_1 \cdot x_{i1} + \dots + \beta_n \cdot x_{in}$$

with \hat{y}_i being the predicted response for the i-th respondent. The constant β_0 and the regression coefficients $\beta_1 \dots \beta_n$ are calculated in a way that the sum of the squared differences between the observed response variable y_i and predicted response variable \hat{y}_i is minimized. Hence, unless all observed responses lay on a straight line, each observed response can differ from its predicted response. The difference between y_i and \hat{y}_i is named the residual, or fitting error, $\hat{\varepsilon}_i$:

$$\hat{\varepsilon}_i = y_i - \hat{y}_i$$

The fitting error $\hat{\varepsilon}_{i}$ is an estimation based on sample data of the of the unknown statistical error ε in the population, which captures the influence of any variables other than the explanatory variables on y. The equation for the observed response variable according to the linear model is thus:

$$y_i = f(x_i) + \varepsilon_i$$

2.2 Generalized Linear Models

Williams et al. (2013) distinguish three categories of assumptions underlying the application of the linear regression to sample data in order to yield valid results. First of all a linear relationship between the response variable y_i and the regression coefficients $\beta_1 \dots \beta_n$ is assumed. Second, the errors ε are required to be independent and normally distributed with a mean of zero and a constant, finite variance across all levels of the explanatory variables. Finally, it is assumed that the explanatory variables are measured without error.

First described in by Nelder and Wedderburn (1972), the Generalized Linear Model (GLM) not only allows non-linear relationships between the response variable and the explanatory variables, but also removes the requirement of having a constant, normally distributed error for all levels of the explanatory variables (Fox, 2008). The GLM consists out of three parts (Agresti, 2015): the random component, the linear predictor and the link function. The random component represents the response variable and its probability distribution. The observed responses are assumed to be independent. The second component is the linear predictor which, similar to a linear model equation, may contain explanatory variables, regression coefficients and constants:

$$\eta_i = \beta_0 + \beta_1 \cdot x_{i1} + \dots + \beta_n \cdot x_{in}$$

Finally, the link function defines how the linear predictor is connected to the mean of the predicted response variable \hat{y}_i thus μ_i It can be specified as:

$$g(\mu_i) = \eta_i = \beta_0 + \beta_1 \cdot x_{i1} + \dots + \beta_n \cdot x_{in}$$

Instead of assuming that the variance of the errors ε is constant across all levels of the explanatory variables, the GLM features a function $var(\mu_i)$ to calculate the variance. The

variance function can either depend on the mean, on the predicted value of the response variable or be a constant.

2.3 Generalized Linear Models with a linear link function

A linear model is the most simple implementation of a GLM as the link function equals the mean predicted response variable μ_i :

$$g(\mu_i) = \mu_i = \beta_0 + \beta_1 \cdot x_{i1} + \dots + \beta_n \cdot x_{in}$$

As noted above, this can also be written as

$$y_i = \beta_0 + \beta_1 \cdot x_{i1} + \dots + \beta_n \cdot x_{in} + \varepsilon_i$$

with the error ε_i having an estimated mean of $\hat{\varepsilon}_i = 0$ and a variance of $var(\varepsilon_i) = var(\mu_i) = \sigma^2$.

2.4 Generalized Linear Models with a logit link function

While linear models can be utilized to predict a continuous, normally distributed response variable, research in social science often calls for the prediction of a dichotomous outcome (Peng et al., 2002). Predicting a dichotomous outcome follows from asking questions such as whether a student will pass a course or whether a teenager will engage in risky behavior. In other words, a dichotomous outcome is either a success or a failure and the researcher is interested in predicting the probability of the observed outcome being a success. Furthermore predicting dichotomous outcomes can help the researcher or stakeholders to take decisions, such as classifying a child as learning disabled.

Logistic regression offers a solution to predict dichotomous outcomes by utilizing the natural exponential function:

$$\mu_{i} = P(Y = 1|X) = \frac{e^{\beta_{0} + \beta_{1} \cdot x_{i1} + \dots + \beta_{n} \cdot x_{in}}}{1 + e^{\beta_{0} + \beta_{1} \cdot x_{i1} + \dots + \beta_{n} \cdot x_{in}}}$$

Here, P(Y = 1|X) is the probability that the outcome is a success for a given vector of X, x_{i1} ... x_{in} are explanatory variables, β_0 is a constant and $\beta_1 \dots \beta_n$ are regression coefficients. The response variable, hence the probability, follows a Bernoulli distribution with a variance of $\mu_i \cdot (1 - \mu_i)$, thus $Y \sim Bernoulli(\mu_i \cdot (1 - \mu_i))$. Translated into a GLM the logistic regression can be specified by the following functions:

$$\eta_{i} = \beta_{0} + \beta_{1} \cdot x_{i1} + \dots + \beta_{n} \cdot x_{in}$$
$$g(\mu_{i}) = logit(\mu_{i}) = \eta_{i} = \log_{e} \frac{\mu_{i}}{1 - \mu_{i}}$$
$$g^{-1}(\eta_{i}) = \mu_{i} = \frac{e^{\eta_{i}}}{1 + e^{\eta_{i}}}$$
$$var(\mu_{i}) = \mu_{i} \cdot (1 - \mu_{i})$$

The link function $g(\mu_i)$ can be any function that maps continuous values from $[-\infty, \infty]$ to [0,1]. However, as a result of its intuitive interpretation as the log of the odds of the successes, thus on average for every failure there will be $\mu_i/(1-\mu_i)$ successes, the logit function is commonly used for this purpose. By applying regression to the linear predictor, the predicted logit can be computed for each level of the explanatory variables. Furthermore, the predicted logit can be converted to a predicted probability value by utilizing the inverse link function $g^{-1}(\eta_i)$. Finally, the variance is calculated based on the predicted probability using the function $var(\mu_i)$.

2.5 Randomized response in Logistic regression models

Under the presumption that the respondent follows the instructions provided by the researcher, van den Hout, van der Heijden and Gilchrist (2007) demonstrated that the Randomized Response (RR) models described by Warner (1965), Boruch (1972) and Kuk (1990) can be represented models by a single equation:

$$P(Y_i^* = 1) = c + d \cdot P(Y_i = 1)$$

 $P(Y_i^* = 1)$ is the probability that the first answer, e.g. "yes", is being observed from the i-th respondent, $P(Y_i = 1)$ is the probability that the *i*-th respondent gives the first answer and the parameters *c* and *d* model the noise that is introduced if utilizing the randomized response technique (RRT) during data collection. Veen (2014) and Fox, Klotzke and Veen (2015) further extended the set of RR models represented by the single equation.

Rearranging the equation to solve for $P(Y_i = 1)$ enables the specification of the according link function in the GLM:

$$\mu_i^* = P(Y_i^* = 1)$$

$$\mu_i = P(Y_i = 1) = \frac{\mu_i^* - c}{d}$$

$$P(Y_i = 0) = 1 - \mu_i = \frac{c + d - \mu_i^*}{d}$$

=> $g(\mu_i^*) = \eta_i = logit(\mu_i) = \log_e \frac{\mu_i}{1 - \mu_i} = \log_e \frac{\mu_i^* - c}{c + d - \mu_i^*}$

The specification of the inverse link function follows the same approach. Given

$$g^{-1}(\eta_i) = \mu_i^*$$

 $\mu_i = \frac{\mu_i^* - c}{d} = \frac{e^{\eta_i}}{1 + e^{\eta_i}}$

the inverse link function is defined as:

$$g^{-1}(\eta_i) = \mu_i^* = c + d \cdot \frac{e^{\eta_i}}{1 + e^{\eta_i}}$$

Likewise, the equation for the variance function can be set up by simply replacing μ_i of the original equation as defined in the GLM with the according term consisting out of the parameters μ_i^* , *c* and *d*:

$$var(\mu_i) = \mu_i \cdot (1 - \mu_i)$$
$$\mu_i = \frac{\mu_i^* - c}{d}$$
$$= > var(\mu_i^*) = \frac{(\mu_i^* - c) \cdot (c + d + \mu_i^*)}{d^2}$$

As Y^* follows from Y, it is also Bernoulli distributed based on the predicted value μ_i^* thus $Y^* \sim Bernoulli(\mu_i^* \cdot (1 - \mu_i^*))$ with $\mu_i^* = c + d \cdot P(Y_i = 1)$.

3. Randomized Response Models

3.1 Warner

Aiming to protect the privacy of the respondents and by that, increasing the response accuracy on sensitive questions, in 1965 Warner proposes the historically first random response (RR) model. In Warner's model each sensitive question comes along with a negotiation of the same. For example, the question "Have you consumed drugs in the past four weeks?" would be presented along with its negotiation "Have you not consumed drugs in the past four weeks?". Using a randomizing device, e.g. rolling a dice, the respondent selects a question to which he provides a truthful answer. The researcher has no insight into the randomizing device and hence does not know to which of the two questions the respondent provided an answer. He however is aware of the probability distribution of the randomizing device and therefore of the probability of the respondent selecting the real question. For example, if the respondent is instructed to select the real question, as opposed to the negotiation, if the dice shows a 2, 3, 4, 5 or 6 then the probability for the respondent to answer the real question is 5/6 and vice versa the probability to choose the negotiated question is 1/6. This can be expressed with equation given in chapter 2.5 of this paper. First of all, if the first answer, e.g. "yes", is observed, it is either possible that it matches the respondent's true answer and he is prompted to respond to the real question or that the respondent's true answer is actually the opposite but he is prompted to answer the negotiated question:

$$P(Y^* = 1) = P(Y^* = 1 | Y = 1) + P(Y^* = 1 | Y = 0)$$

With *p* being the probability that the randomizing device leads to instructing the respondent to answer the real question and π being the true probability of giving the first answer to the real question, thus *P*(Y = 1) the equation for *P*(Y^{*} = 1) is as follows:

$$P(Y^* = 1) = p \cdot \pi + (1 - p) \cdot (1 - \pi)$$

<=> $P(Y^* = 1) = \pi \cdot (2p - 1) + (1 - p)$

Finally, the parameters *c* and *d* are defined as (1 - p) respectively (2p - 1), which leads to the following equation:

$$P(Y^* = 1) = \pi \cdot d + c$$

<=> $P(Y^* = 1) = c + d \cdot P(Y = 1)$

In the aforementioned example of rolling a dice to select either the real question or its negotiation, *c* would hence equal 1 - 5/6 = 1/6 and *d* equals 2 * 5/6 - 1 = 2/3.

3.2 Forced-Response

Contrary to Warner's model, the forced-response (FR) model, as described by Boruch (1972), relies on prompting a single, sensitive question to the respondent. Using the randomizing device, in which the researcher has no insight, the respondent is instructed to reply with either "yes", "no" or either "yes" or "no" based on his truthful answer. If a dice is utilized as randomizing device, the respondent could for example be instructed to reply with "yes" if the outcome of the dice is a 1, to reply with "no" if the outcome is 6 and to reply truthfully with either "yes" or "no" if the dice shows a 2, 3, 4 or 5.

With the known probability of an instructed "yes" or "no" reply being p_y respectively p_n , the probability of a truthful answer is $1 - p_y - p_n$. From that follows that the probability for an observed "yes" is the sum of the probability for the respondent to answer truthfully with "yes" and the probability of a forced "yes" reply, thus p_y . Defining *c* as equaling p_y and *d* as equaling $1 - p_y - p_n$ shows that the FR model can be represented by the following equation:

$$P(Y^* = 1) = \pi \cdot (1 - p_y - p_n) + p_y$$

<=> $P(Y^* = 1) = \pi \cdot d + c$
<=> $P(Y^* = 1) = c + d \cdot P(Y = 1)$

3.3 Two Bernoulli distributions

Kuk (1990) offers an RR model in which two separate Bernoulli distributions are used to add noise to the true answer of the respondent. First, the respondent faces a question that can be answered with either "yes" or "no". Next, the respondent is provided with two binary outcomes that differ in their probability distribution. A concrete example are two packs of cards. Each pack is shuffled and consists out of blue and yellow cards with the ratio of blue versus yellow cards differing between the packs. In other words, drawing a card from each pack leads to two binary outcomes, namely blue or yellow, and the probability for the drawn card to be blue is higher in one pack. If the respondent's true answer to the question is "yes", then he is asked to show the card drawn from the first pack to the researcher and likewise, if the respondent's true answer is "no", he shows the card drawn from the second pack. The researcher has no knowledge about from which pack the card shown to him was drawn.

However, as he is aware of the proportion of blue versus yellow cards in each of the two packs, he possesses insight into the probability distributions of the outcomes.

Let θ_1 and θ_2 be the known proportion of blue cards in the first respectively second pack, p_1 and p_2 are therefore the probabilities to draw a blue card from the first respectively second pack and π being the probability that the respondent would answer with "yes" to the question. With defining c as equaling p_2 and d as equaling $(p_1 - p_2)$, Kuk's model can be represented by the following equation:

$$P(Y^* = 1) = P(Y^* = 1 | Y = 1) + P(Y^* = 1 | Y = 0)$$

<=> $P(Y^* = 1) = p_1 \cdot \pi + p_2 \cdot (1 - \pi)$
<=> $P(Y^* = 1) = \pi \cdot (p_1 - p_2) + p_2$
<=> $P(Y^* = 1) = \pi \cdot d + c$
<=> $P(Y^* = 1) = c + d \cdot P(Y = 1)$

4. Problem description

4.1 Hypothesis testing and model choice

Goodness-of-fit tests indicate how well a statistical model fits the observed data. In this simulation the observed data is generated based on the inverse link function which maps the linear term of explanatory variables and their coefficients thus $\eta_i = \beta_0 + \beta_1 x_{i1} + \cdots + \beta_n x_{in}$ to a probability, hence to values between 0 and 1. For the logit link function the formula looks as follows:

$$g^{-1}(\eta_i) = c + d \cdot \frac{e^{\eta_i}}{1 + e^{\eta_i}}$$

Writing the formula in a more general way shows that the mapping can be done with any link function that maps continuous values from $[-\infty, \infty]$ to [0,1]:

$$P(Y^* = 1) = c + d \cdot P(Y = 1)$$

Two types of statistical models are used in this paper: First of all, the true model which fully matches reality and therefore can predict the observed data accurately. In other words, it contains the complete term of explanatory variables and accurate regression coefficients. For the purpose of this simulation the true model will therefore use the complete set of explanatory variables $x_{i1} \dots x_{in}$ and the restricted model contains an incomplete set of explanatory variables. To illustrate this with a practical example in which the observed data is generated with two explanatory variables, x_{i1} and x_{i2} : the true model contains the linear prediction term $\eta_i = 0.2 + 0.4 * x_{i1} - 0.17 \cdot x_{i2}$ while in the restricted model the effect of the second predictor x_{i2} is fixed to zero, leading to a linear term based on only the first predictor x_{i1} , e.g. $\eta_i = -0.1 + 0.6 \cdot x_{i1}$.

Two tests for statistical significance can be described. Considering that the true model matches the model used for simulating the data, a goodness-of-fit test should not indicate a statistical significant difference between the observed data and predictions from the true model. In terms of the null hypothesis H₀ and an alternative hypothesis H_a, this can be formulated as follows: H₀: there is no significant difference between the observed data and the predictions of the true model. H_a: there is a significant difference between the observed data and the predictions of the true model and therefore an alternative model fits the data better than the specified true model.

If this test leads to the incorrect conclusion that H_0 must be rejected when the true model is equal to the model used for generating the data, a so-called type-1 error is made.

The second test concerns the restricted model, which by definition differs from the model used for generating the data. The corresponding hypotheses are as follows: H₀: there is no significant difference between the observed data and the predictions of the restricted model. H_a: there is a significant difference between the observed data and the predictions of the restricted model.

Considering that by definition the restricted model does not fit the data as accurately as the model used for generating the data, a goodness-of-fit test should lead to the conclusion that H_a is true and thus that H_0 should be rejected. If the conclusion is however that the restricted model fits the data well enough, then a so-called type-2 error is made. Furthermore, the statistical power of a test is defined as 1 - the fraction of type-2 errors and hence the statistical power of a test declines as more type-2 errors occur.

4.2 Measures of goodness-of-fit

For categorical data the Pearson and Deviance goodness-of-fit tests are utilized. While the exact procedure to compute the goodness-of-fit differs between those two measures, the general approach is very similar. In short, based on the observed group mean probability \bar{y}_i^* and the predicted group mean probability $\hat{\pi}_i^*$ the difference between the observed data and the predictions is computed. As discussed in more detail in the next paragraph, here, each group consists out of respondents that share the same combinations of explanatory variables. In simplified terms, the respondents who share the same set of characteristics are grouped together. For each group, the difference between \bar{y}_i^* and $\hat{\pi}_i^*$ is furthermore scaled by the estimated standard deviation within that group. The Pearson statistic X_P^2 is computed as follows, with n_i being the number of respondents in the *i*-th group:

$$X_P^2 = \sum_{i=1}^N n_i \cdot \frac{(\bar{y}_i^* - \hat{\pi}_i^*)^2}{\hat{\pi}_i^* \cdot (1 - \hat{\pi}_i^*)}$$

For more information on the Pearson and Deviance goodness-of-fit tests see Tutz (2011, pp. 87-91).

Each of the explanatory variables $x_{i1} \dots x_{in}$ represents a certain characteristic of the *i-th* respondent. For example the first explanatory variable x_{i1} could contain the age of the respondent and the second variable x_{i2} could represent his or her gender. If x_{i2} takes the value 0 for a male and 1 for a female gender, a 30 year old woman would be represented by $x_{i1} = 30$ and $x_{i2} = 1$. Furthermore this woman would have either a positive observed outcome, i.e. $y_i = 1$ or a negative outcome, i.e. $y_i = 0$. Repeating the same procedure for n - 1 more respondents would result in a total of n individual combinations of x_{i1} , x_{i2} and y_i . However, for the Pearson and Deviance statistics the degrees of freedom increase along with the sample size n. As the Pearson test statistic X_p^2 is not guaranteed to be asymptotical chi-squared distributed for a large degree of freedom, its value cannot be safely evaluated. The same accounts for the Deviant test statistic X_D^2 (Tutz, 2011, pp. 89-90). The solution is to group the respondents based on their characteristics. In the former example with two explanatory variables, the respondents who share the same value of x_{i1} and x_{i2} , would be placed in the same group, or cluster. For example one cluster contains all 40 year old males, the next cluster contains all 35 year old females and so on.

Under the assumption that each cluster contains more than one respondent, for each characteristic, thus combination of explanatory variables, multiple observations are available. Each cluster with *i* respondents contains n_i trials for a given combination of explanatory variables and the outcome of a trial is either a 1 or 0, thus a success respectively a failure. In other words, the Bernoulli distribution with a single trial for each respondent has been transformed to a Binominal distribution for each cluster with n_i trails and an estimated group mean probability $\hat{\pi}_i$, resulting in $y_i \sim B(n_i, \hat{\pi}_i)$. As the number of clusters is fixed, the test statistic values X_P^2 and X_D^2 can be evaluated with a chi-squared distribution with $N \cdot P$ degrees of freedom, N being the number of non-empty clusters and P being the number of estimated parameters.

While the Pearson and Deviance statistics are designed for categorical data, they can also, to some degree, be applied to continuous variables. In the former example the variable age is continuous but is treated as categorical due to its discrete character and its fixed number of possible values, or levels. A continuous variable with a great number of levels would however strongly increase the number of clusters and as a result the degrees of freedom of the chi-squared distribution would no longer be fixed. The Hosmer-Lemeshow (H-L) test approaches this difficulty by offering an alternative way to group the respondents into clusters. The Hosmer-Lemeshow test is a modified Pearson goodness-of-fit test but in place

of grouping respondents based on their shared explanatory variables, the researcher can choose the number of clusters. The procedure is as follows: first of all, the respondents are ordered based on their predicted probability of success. As discussed earlier, the predictions are made for each respondent based on his characteristics, hence his combination of explanatory variables. Next, the respondents are grouped into *N* clusters of equal size, with the *n* / *N* respondents with the lowest predicted probability of success entering the first cluster, the following *n* / *N* respondents based on the same criteria enter the next cluster and so on. Finally, the Pearson statistic can be computed for the chosen set of clusters:

$$X_{HL}^{2} = \sum_{i=1}^{N} n_{i} \cdot \frac{(\bar{y}_{i}^{*} - \hat{\pi}_{i}^{*})^{2}}{\hat{\pi}_{i}^{*} \cdot (1 - \hat{\pi}_{i}^{*})}$$

The resulting test statistics X_{HL}^2 is chi-squared distributed with *N* - 2 degrees of freedom. For more information about the Hosmer-Lemeshow test see Tutz (2011, pp. 92-93).

Goodness-of-fit test statistics offer an indication about how well a statistical model fits the observed data on a global level. However, often it is of interest to examine where exactly the model does or does not fit the observed data. For this purpose, residuals are calculated. Residuals show the discrepancy between the observed and the predicted values, either for each individual respondent or per cluster. Furthermore, residuals are usually scaled by the estimated standard deviation for the particular respondent or cluster. In this paper, the scaled Pearson residual is utilized, which takes the same parameters \bar{y}_i^* , $\hat{\pi}_i^*$ and n_i as the earlier described Pearson statistic to compute the discrepancy between the predicted and observed mean cluster probabilities (Tutz , 2011, pp. 93-94):

$$\tau_P(\bar{y}_i^*, \hat{\pi}_i^*) = \frac{\bar{y}_i^* - \hat{\pi}_i^*}{\sqrt{\hat{\pi}_i^* \cdot (1 - \hat{\pi}_i^*)/n_i}}$$

4.3 Goodness-of-fit tests for RR models for binary data

By the time of writing this paper, there was no description of goodness-of-fit tests for RR models for binary data available in the literature. The following section provides an explanation on how existing goodness-of-fit tests for binary data, i.e. the Pearson statistic and the Deviant statistic, can be utilized to evaluate the goodness-of-fit of RR models.

With binary data, the parameter \bar{y}_i^* contains the observed mean probability of success for a given cluster. Where the observed data \bar{y}_i^* is influenced by the RR design, the RR model with parameters *c* and *d* is given by:

$$P(Y^* = 1) = c + d \cdot P(Y = 1)$$

and it follows that with \bar{y}_i being the true group mean probability:

$$\bar{y}_i^* = c + d \cdot \bar{y}_i$$

However, the specified glm link function is adjusted to include the influence of the RRT, also by including the parameters *c* and *d*:

$$g^{-1}(\eta_i) = c + d \cdot \frac{e^{\eta_i}}{1 + e^{\eta_i}}$$

Therefore, with $\hat{\pi}_i$ being the predicted mean probability of success for a given cluster, without RR influence:

$$\hat{\pi}_i^* = c + d \cdot \hat{\pi}_i$$

It follows that the observed data can be compared to the predictions without requiring a modification of the Pearson or Deviance goodness-of-fit measures.

4.4 Evaluating the goodness-of-fit of one model against a single alternative

Goodness-of-fit tests evaluate the model against an unspecified alternative model, and therefore these tests will have poor statistical power. Reliably detecting a discrepancy between the inaccurate model and the observed data is referred to as strong statistical power. However, in practice there is often more than one proposed statistical model to describe the observations. It is then of interest to evaluate which of the models describes the observed data best. The Pearson, Deviance and Hosmer-Lemeshow test statistics, which are chi-squared distributed, can be used to indicate how well a model fits the observed data. It seems straightforward to compare the value of a test statistic of two competing models to examine which of the models fits the data better. And indeed, after scaling two independent chi-squared variables for the degrees of freedom of their corresponding distribution, a F-distributed ratio variable can be computed (Devore & Berk, 2012, pp. 323-325). Let X_P^2 and X_P^2 be the Pearson test statistics for the true model and a restricted model and df_T and df_R be the respectively degrees of freedom of their distribution. From that follows:

$$F_{df_R,df_T} = \frac{X_{P\ R}^2/df_R}{X_{P\ T}^2/df_T}$$

The ratio variable is thus F-distributed with the degrees of freedom df_R and df_T . If the pvalue stemming from the F-distribution for the ratio variable is smaller than the specified level of significance α , then the true model fits the data significantly better in comparison with the restricted model. In terms of statistical hypotheses the null hypothesis states thus that no significant difference exists between the goodness-of-fit of the true model and the restricted model. Accordingly, the alternative hypothesis is accepted if the true model fits the data better than the restricted model.

If both models share one or more explanatory variables, independence of the chi-squared variables in the nominator and denominator can be questioned. The reason for this is that the predictions of a model are strongly based on the explanatory variables. However, as the test statistics are based on the scaled residuals, the test statistics of two models are independent if for both models the residuals are independent of the predicted values. In more general terms, for each individual respondent a predicted probability of success is calculated by the model based on his combination of explanatory variables. Next, the discrepancy between the observed outcome for this respondent and his predicted probability of success is calculated in the form of a residual. Finally, based on the residuals of all respondents or clusters the test statistic is computed. Therefore, if the distribution of the residuals is independent of the predictions made by the model, then any variable that is based on the residuals is also independently distributed. Put simply, if the residuals of the first model do not convey information over the residuals of the second model then the test statistics that are computed based on said residuals are independent.

4.5 Research question

The main research question for this paper is if the Pearson, Deviance and Hosmer-Lemeshow tests are suited to evaluate the goodness-of-fit of RR models for binary data. This can furthermore be split into following sub-questions:

- Do the type-1 and type-2 error rates change in an RR design with categorical data, and in what way?
- Do the type-1 and type-2 error rates change in an RR design with continuous data, and in what way?

5. Method

5.1 Procedure and technical implementation in R

As shown in Figure A, the simulation consists of five modules. Each of the modules is implemented in the statistical programming language R. The central module generates the data based on a link function, an RR design and various user settings. Next, through interaction with the goodness-of-fit testing module it computes the type1-error rate and the statistical power for the given data. Finally the results are printed and saved.

The link function can be any glm link function that maps continuous values from $[-\infty, \infty]$ to [0,1]. Examples are the logit and the probit link function. Any RR design modeled by the parameters *c* and *d* can be used in the simulation, e.g. Warner's design and the Forced Response design. Three goodness-of-fit tests are implemented for the purpose of the simulation, namely the Pearson statistic, the Deviance statistic and the Hosmer-Lemeshow statistic. User settings include a set of predictors and coefficients defining the true model, the number of samples, the sample size, the level of significance and the RR parameters *c* and *d*.

Figure A

Simulation modules design diagram



5.2 Randomized Response designs

The collection of data is based on Warner's RR design. The central parameter in Warner's design is the probability p of presenting the true question to the respondent. When modeling the probability p by the parameters c and d, c = 1 - p and d = 2 * p - 1. In the simulation a non-RR design is compared to two Warner's RR designs, see Table A.

Design d р С No RR 1 0 1 Warner .9 .1 .8 Warner .2 .8 .6

Table AData collection designs with parameters c and d

5.3 Components of the simulation

The simulation consists of two parts, aimed at different components of the research question: logistic regression with categorical predictors and logistic regression with a continuous predictor and controlled cluster size. Each part is carried out with a separate function, implemented in the statistical programming language R. If not stated otherwise, the term goodness-of-fit tests comprehends the Pearson, the Deviance and the Hosmer-Lemeshow tests. By default the Hosmer-Lemeshow test groups the respondents into 10 clusters. A significance level of $\alpha = .05$ is applied.

5.3.1 Logistic regression with categorical predictors

In the first part of the simulation it is examined in what way an RR design affects the type-1 error rate and the statistical power of goodness-of-fit tests when using solely categorical predictors to generate the data.

The true model is based on two categorical predictors, x_1 , and x_2 with respectively 5 and 2 levels:

x1 = sample(0:4,nRespondents,replace=T)
x2 = sample(1:2,nRespondents,replace=T)

The data is generated as follows:

eta = 3.5 * x1 - 6.0 * x2
prob = c + d * exp(eta)/(1 + exp(eta))
y = rbinom(nRespondents,size=1,prob=prob)

Alternatively, for Warner's RR design the inverse link function can be written as:

prob = (1 - p) + (2*p - 1) * exp(eta)/(1 + exp(eta))

The restricted model is based solely on x_1 , thus restricting the effect of x_2 to zero when predicting the data. For each of the three data collection designs (see Table A), three times 10000 samples are simulated, with respectively n = 500, n = 1000 and n = 1500 respondents. The Pearson and Deviance goodness-of-fit tests are utilized.

Additionally, following the procedure described in chapter 4.4 of this paper, the goodnessof-fit of the true model is evaluated against a single specified alternative, namely the restricted model. Ideally the true model should be preferred over the alternative in all circumstance, i.e. across all analyzed data collection designs and sample sizes. Again, for each of the three data collection designs three times 10000 samples are simulated, with respectively n = 500, n = 1000 and n = 1500 respondents. The procedure is executed based on the Deviance test statistic.

5.3.2 Logistic regression with a continuous predictor and controlled cluster size

The aim of the second part is to assess in what way an RR design affects the type-1 error rate and the statistical power when using a categorical predictor and a continuous predictor to generate the data. To control the cluster size, the Hosmer-Lemeshow goodness-of-fit test is applied with respectively 4, 5, 8, 10, 20, 25, 40, 50, 100, 200 and 250 groups.

The true model is based on a categorical predictors x_1 with 5 levels, and a continuous predictor x_2 :

x1 = sample(-2:2,nRespondents,replace=T) x2 = runif(nRespondents,-1.5,1.5) x2 = x2[order(x2)]

The linear predictor function to generate the data looks as follows:

eta = $1.2 \times x1 - 0.5 \times x2$

The restricted model is based solely on x_1 , thus restricting the effect of x_2 to zero when predicting the data. For each of the three data collection designs 10000 samples with n = 1000 respondents are simulated.

6. Data analysis

6.1 Logistic regression with categorical predictors

Applying the Pearson and Deviance goodness-of-fit tests to a model with two categorical predictors revealed a distinct patter in the statistical power of the test across the three data collection designs. While the power is the highest in a non-RR data collection design, lowering Warner's probability p of presenting the real question to the respondent results in a lower power among RR designs. In other words, goodness-of-fit tests applied to data gained from an RR design with p = .8 show a lower statistical power than tests applied to data with p = .9. As the amount of variance that an RR design adds to the data is directly linked to its degree of randomization, in the case of Warner's design thus modeled by p, these results were expected. More variance, or noise in the data leads to a reduction in information about the underlying statistical model and therefore results in less power to reject the incorrect model. However, at a sample size of n = 1500, the RR design with p = .9 reaches a statistical power of .99 which equals the baseline that was set by the non-randomized data. The results do not significantly differ between the Pearson and the Deviance test.

The examination of type-1 errors yielded surprising results, with the error rate decreasing for the Pearson test as the degree of randomization increases. The Deviance test showed the same pattern between the two RR designs with p = .8 and p = .9, however the error rate is significantly lower for the data obtained without randomization. The results are in contradiction with the opposite pattern of statistical power for the same data. Thus, a possible explanation is that the additional variance leads to a slight underestimation of the type-1 error rate for this data at the chosen sample sizes. Despite the difference, neither the Pearson nor the Deviance statistic provided results that indicated a significant lack of fit of the true model with either the non-RR design or the RR designs.

Figure B and Figure C illustrate the results. Each point on the plots represents the average percentage of type-1 error respectively the average statistical power across 10000 bootstrap samples for a combination of sample size (n = 500, n = 1000, n = 1500) and data collection design (p = 1, p = .9, p = .8). A significance level of $\alpha = .05$ was applied.

Setting the Pearson residuals against the fitted values for 20 random samples of size n = 50 for each of the three data collection designs (p = 1, p = .9, p = .8) showed a possible

correlation between the residuals of the true model and the residuals of the restricted model at fitted values nearby 0 and 1. Taken into account that a Pearson residual for an observation that is close to 0 cannot take large positive values and likewise residuals for observations nearby 1 cannot take large negative values, the distinct pattern at the tails can possibly be explained. However, independence is not proven. When evaluating the goodness-of-fit of the true model against the restricted model in a non-RR design with a significance level of α = .05, for a sample size of n = 1000 the true model is detected to fit the observed data significantly better than the restricted model in approximately 91% of the cases. The detection rate became significantly worse in an RR design as the degree of randomization was increased (for n = 1000; p = .9: 49%; p = .8: 21%). Using a larger sample size of n = 1500 respondents raised the detection rate significantly for the randomized data (for n = 1500; p = .9: 72%; p = .8: 38%). The results indicate that the noise added by randomizing the data reduces the reliability with which the goodness-of-fit of one model can be evaluated against a specified alternative model and thus confirm the findings that were made through evaluating the statistical power with similar data. See Figure E for an illustration of the results. The estimations are based on 10000 bootstrap samples for each combination of sample size (n = 500, n = 1000, n = 1500) and data collection design (p = 1, p = .9, p = .8).

6.2 Logistic regression with a continuous predictor and controlled cluster size

When replacing the second categorical predictor with an ordered continuous predictor, the Hosmer-Lemeshow goodness-of-fit test shows a significant discrepancy in the estimated statistical power for a sample size of n = 1000 respondents between the three data collection designs (p = 1, p = .9, p = .8). Across most cluster sizes, the statistical power noticeably declines as the randomization becomes stronger, thus confirming that the noise added by the RRT leads to a reduction in power to reject the incorrect model (see Figure F). As shown in Figure G, no noticeable difference between the estimated percentage of type-1 errors was found between the three data collection designs. Each line in Figure F and G is an estimation based on mean data from 10000 bootstrap samples and thus each point of the plots represents the average percentage of type-1 error respectively the average statistical power across 10000 samples for a defined number of clusters.

See Table B and Table C for an overview of the type-1 error rate respectively the statistical power across both parts of the simulation.

Table B

Predictors	Sample size		Type-1 error	rate
(Test statistic)				
		No RR	p = .9	p = .8
Two categorical	500	6.2 (0.5)	4.8 (6.1)	4.3 (4.8)
predictors	1000	6.6 (0.8)	5.0 (5.1)	4.2 (4.6)
(Pearson/Deviance)	1500	8.1 (1.0)	4.8 (5.2)	4.8 (4.9)
One categorical, one continuous predictor (H-L, N = 10)	1000	4.1	4.6	4.3

Type-1 error rate for RR data collection designs compared to a non-RR design

Table C

Statistical power for RR data collection designs compared to a non-RR design

Predictors	Sample size		Power	
(Test statistic)				
		No RR	p = .9	p = .8
Two categorical	500	.98 (.99)	.39 (.41)	.25 (.26)
predictors	1000	.91 (.96)	.60 (.62)	.42 (.44)
(Pearson/Deviance)	1500	.99 (.99)	.99 (.99)	.75 (.75)
One categorical	1000	88	55	29
one continuous	1000	.00	100	
predictor				
(H-L, N = 10)				



Figure B Type-1 errors for categorical predictors and different RR designs



Figure C Statistical power for categorical predictors and different RR designs







Figure E Goodness-of-fit of the true model against a single incorrect alternative



Figure F Statistical power for different RR designs across different cluster sizes



Figure G Type-1 errors for different RR designs across different cluster sizes

7. Discussion

The main research question for this paper was if the Pearson, Deviance and Hosmer-Lemeshow tests are suited to evaluate the goodness-of-fit of RR models for binary data. For this purpose, it was examined if and in what way an RR design affects the type-1 error rate and the statistical power when working with categorical respectively continuous data.

7.1 Do the type-1 and type-2 error rates change in an RR design with categorical data,

and in what way?

There was no evidence found indicating that the type-1 error rate is significantly higher or lower in RR data collection designs compared to non-randomized data collection designs. However, while the type-1 error rate computed with the Pearson statistic was slightly higher for the non-RR design compared to the RR designs, it was noticeably lower when utilizing the Deviance statistic. Despite the difference, neither the Pearson nor the Deviance statistic provided results that indicated a significant lack of fit of the true model with either the non-RR design or the RR designs.

For both test statistics the statistical power to reject an incorrect model declined as the degree of randomization of the data was increased. When evaluating the true model against a single, incorrect alternative model the results followed the pattern found in the statistical power.

7.2 Do the type-1 and type-2 error rates change in an RR design with continuous data, and in what way?

Simulations made with continuous data did not reveal a significant difference in the type-1 error rate between RR designs and non-RR designs. The statistical power declined with the degree of randomization of the data being increased. The results for both the type-1 error rate and the type-2 error rate have been confirmed across various cluster sizes.

7.3 Conclusion

Based on the results of this simulation study, the Pearson, Deviance and Hosmer-Lemeshow tests are suited to evaluated the goodness-of-fit of RR models for binary data when using an adjusted logit link function. No significant difference was found for the type-1 error rate for RR models and the discrepancy in statistical power was expected as the RRT by design introduces noise to the data. More variance, or noise in the data leads to a reduction in information about the underlying statistical model and therefore results in less power to reject the incorrect model. While the variance in the data increased in RR designs, no indication of systematic bias was observed. Additional testing is required to confirm the assumption that the results can be reproduced for different link functions.

It must be noted that in the aforementioned approaches to evaluate in what way an RR design affects the working of goodness-of-fit tests a worst case scenario for the RRT was assumed: while it did add noise to the collected data, it did not affect the response behavior of the respondents. However, strong evidence exists supporting that assumption that respondents answer more truthfully to sensitive questions in an RR design. For example, if 70% of the respondents provide a truthful answer to a particular question, this percentage might raise to 90% in an RR design. In other words, at that point in the procedure of collecting data, the observations made in an RR design are less prone to variance. Obviously the RRT by design introduces noise to the data, and thereby increases the variance at a later point. However, while it is often difficult for the researcher to estimate the rate of truthful responses, the variance added by an RR design is known and can be modeled. The known variance of an RR design is therefore to be preferred over the unknown variance that stems from whether or not a respondent is willed to answer truthfully. To sum up, the results obtained in this paper indicate that the randomization of the data can be modelled well, however in a real-world scenario the utility of the RRT will greatly depend on the researcher's ability to choose an RR design that significantly promotes response accuracy.

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