



Model-based redesign of a self-balancing scooter

Teun van Kuppeveld

MSc Report

Supervisors:

prof.dr.ir. J. van Amerongen

dr.ir. J.F. Broenink

ir. M.A. Groothuis

dr.ir. A.M. Bos

August 2007

Report nr. 022CE2007

Control Engineering

EE-Math-CS

University of Twente

P.O.Box 217

7500 AE Enschede

The Netherlands
